











# **Application of aerial remote sensing** technologies in sustainable water management

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www.envirosense.hu

Research Institute of Remote Sensing and Rural Development















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# Overview

Introduction of organisations

- Technical background
  - Airborne sensors
  - Field measurments
  - · Data processing
- · Case studies

















# Introduction Eszterházy Károly University Research Institute of Remote Sensing and Rural Development

Mission: **EKU RIRSRD** to conduct basic & applied RS research for the advancement of scientific knowledge about the environment.

Team responsible for conducting all phases of RS operations (*flight/mission planning, sensor maintenance, data acquisition, data processing, data analysis and modelling*)

### 10+ years experience:

- R+D projects
- Hyperspectral imagery
- LIDAR and orthophoto
- Image processing







# Introduction Eszterházy Károly University Research Institute of Remote Sensing and Rural Development



UNITED NATIONS | UNOOSA | UN-SPIDER

United Nations Platform for Space-based Information for Disaster Management and Emergency Response



## INSTITUTIONAL SUPPORT OF THE DISASTER AND EMERGENCY RESPONSE PROGRAM OF THE UNITED NATIONS – UN SPIDER









#### United Nations Office for Outer Space affairs (UNOOSA) I.

UNOOSA is the United Nations office responsible for promoting international cooperation in the peaceful uses of outer space.

UNOOSA conducts international workshops, training courses and pilot projects on topics that **include remote sensing, satellite navigation, satellite meteorology, tele-education and basic space sciences** for the benefit of developing nations. It also maintains a <u>24-hour hotline as the United Nations</u> <u>focal point for satellite imagery requests during disasters</u> and manages the United Nations Platform for Space-based Information for Disaster Management and Emergency Response (UN-SPIDER).

















# Introduction Envirosense Hungary Ltd

Envirosense Hungary Ltd.  $\rightarrow$  spin off established in 2009.

- specialist of remote sensing, **production and processing** of images by **aerial** sensors
- Remote sensing **devices**:
  - aerial hyperspectral
  - airborne LiDAR technologies
  - digital imagery +processing of UAV and satellite images.

### Fields of activities:

- Environmental protection / Nature conservation
- Forestry
- Agriculture
- Urban development
- Mining
- etc.







Flight

Line

Spatial Pixels

Single Pixel

Series of Sensor Frames

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Pixel Spectrum

Wavelength

Spectral Bands

Single Sensor Frame

What is spectral imaging? (hyperspectral imaging, imaging spectroscopy)





Each pixel is associated with simultaneous high resolution spectral information produced by a spectral camera















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Airborne remote sensing

Hyperspectral imagery

(Sajó valley, Hungary)

Hyperspectral image in different displays

MNF (militeithälisflafiteithälisflafiteithälisteit



















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# Airborne remote sensing Hyperspectral imagery



nm





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Development



# Airborne laser scanning (LiDAR) (Light Detection And Ranging)



# Data processing



# Processing of LIDAR data and aerial digital images













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# Airborne remote sensing Advantage of LIDAR and aerial digital imagery

- Producing **DSM** and **DTM**, especially in **forested areas**
- High accuracy and very dense measurement applications, e.g., DTM generation and volume calculation in open pit mines, waste deposits, forest parameters
- DTM and DSM generation in **urban areas**, generation of **3D city models**
- Mapping of **corridors**, e.g., roads, railway tracks, pipelines, waterway landscapes
- Mapping of **electrical power lines** and **towers** including tree clearance
- Mapping **large area** (500-1000 km2/day)











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Cross-section generator application from LIDAR data

Integreted to ArcMap software •



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Ground based measurements Airborne laser scanning (LIDAR) and aerial digital imagery



- Reference points surveys with high accuracy DGPS
- Collecting GNSS data with base station (during airborne acquisition and post-process)
- Airborne hyperspectral imagery :
  - Reference surveys with field spectrometer
  - Study and controll sites survey with DGPS
  - Collecting ground samples (ASD FieldSpec3, etc)
    - In situ measurments (WALZ Mini-Pam, etc.)











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# Data processing Techniques and devices















- **SGI supercomputer** SGI UV 2000 (24 db 2,4GHz Intel Xeon E5-4610 type CPU-144 core, total:1536 GB RAM)
- SGI Octane III high-performance graphics workstations
- SGI C2108-TY11 server
- SGI C1104-2TY9 dual-node server
  - **RAID** storage





















# Case study I.

ASSESMENT OF FLOOD PROTECTION POTENTIALS IN THE SAJÓ VALLEY BY MEANS OF R/S SURVEYS

Aim of the project

Improvement of flood protection and river basin management capabilities and Improvement of the conditions of environmental protection and nature conservation of the crossborder region

















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# River basin management and flood protection are very important in Hungary























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- hyperspectral imaging system (AISA)
- aerial laser scanning system (LEICA)
- digital camera (LEICA)
- in addition GCP and field spectrophotometer













Hyperspectral data aquisition

#### Main parameters:

OxTS RT 3003 high accuracy GPS/INS



Spectral range: 400-2450nmSpectral sampling: 2.5-10nmNumber of spectral bands: 128-498Swath width: 1024pixelScan rate: max. 150HzRadiometric resolution: 12bit











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# LiDAR and digital orto photo













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Leica ALS-70 HP and Leica RCD 30 RGBN powerful digital aerial LIDAR sensor with builtin high precision GPS/INS system and 60 MP orthocamera



Maximum Flying Height (m AGL)	3500	
Maximum Measurement Rate (kHz)	500	
Field of view (degrees)	0–75 (full angle, user adjustable)	
Roll stabilization (automatic adaptive, degrees)	75–active FOV	
Scan patterns (user selectable) Maximum Scan Rate (Hz)	single	200
	triangle	158
	raster	120
Numbers of returns	unlimited	
Number of intensity measurements	3 (first, second, third)	
Accuracy	see graph	
Storage media	removable 500 GB SSD	
Storage capacity (hours @ max measurement rate)	6	





60 MP resolution (8956 x 6708 pixel) Up to 4 cm GSD Spectral resolution: RGB and NIR (780 - 900 nm) 50 mm focal length objective

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#### Softwares used:

- ESRI ArcGIS 10.2
- ENVI/IDL 5.0
- Trimble eCognition 8.8
- OPALS (TU Wien)

# **Results:**

Data processing

- Radiometric and geometric correction
- supervised classification
- object based image analysis
- normalized digital surface models





300 Gb of hyperspectral data Spectral range: 400 – 970 nm Spectral band width: 4,6 nm Number of spectral bands: 128 Pixel size: 1,5 m































IUIAI UALA SIZE. 700 GD



















# LIDAR based DTM of the total surveyed area















- 5 point/m<sup>2</sup>
- classified pointcloud
  - from 300 km<sup>2</sup> area more than 2 billion points recorded Digital Terrain Model
  - Digital Surface Model







# Vegetation map based on LiDAR & Hyperspectral data











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Vegetation and biomass map



















#### **Modelling the use of emergencyflood water reservoirs**



















Case study II.

# Updating the flood-control plans on sections of River Tisza

Trans-Tisza Region Water Directorate (TIVIZIG) and North-Hungarian Water Directorate (ÉMVIZIG)





## Aim of the project

Updating flod-control plans















Mission:

- Airborne laser scanning (LIDAR)
- Aerial digital imagery (orthophoto production)
- Aerial hyperspectral imagery
- Landuse mapping and biomass estimation
- Ground based geodetic survey and data collection
- Bursting of dam simulation
- Compiling documentation of flood-control plan





#### The surveyed area (section of River Tisza, Hungary)

Észak-Magyarországi Környezetvédelmi és Vízügyi Igazgatóság

Délborsodi ártéri öblözet















Floodplain bays impacted by the project



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Tiszántúli Környezetvédelmi és Vízügyi Igazgatóság

Tiszalőki ártéri öblőzet

Hortobágyi ártéri öblözet



# Applied remote sensing technolog LiDAR and aerial digital imagery device

#### LIDAR sensor (RIEGL LMS-Q680i) parameters:

Range of the laser  $\rightarrow$  up to 5000 m Recommended maximum flight high  $\rightarrow$  up to 3000 m above the ground Laser impulse range  $\rightarrow$  80 – 400 kHz Scanning frequency  $\rightarrow$  0 - 70 kHz Field of view (FOW)  $\rightarrow$  30 -60° Multiple echoes per impulse  $\rightarrow$ 1 - 4

> Ortho images made with Leica RCD105 digital medium format camera together with LiDAR survey







Georeferenced point cloud:

(horizontal / vertical)

DTM, DSM, nDSM files

ground resolution: 10 cm

**Orthophoto TIFF-s:** 

5700 images

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average point density: 4 points/m2

420 pcs UTM projection, LAS files

transverse overlap: 30% (average)

longitudinal overlap: 60% (average)











#### Airborne laser scanning (LIDAR) and aerial digital imagery Acquisition and results

#### **Project area and flight lines**



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#### **3D image of LIDAR point cloud**





















































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#### LIDAR point cloud Plan view





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#### **Orthophoto and its enlarged details**

























#### **RGB and NIR ortho images**























LIDAR image







**TIN model** (triangulated irregular network)





Applied remote sensing technologies Airborne hyperspectral imagery devices



AISA Dual K1 hyperspectral sensor with high accuracy GPS/INS system (Oz RT 3003)

AISA Eagle (VNIR) + AISA Hawk (SWIR)



Parameters:

Spectral range: 400-2450nm Spectral band: 128-498 Bar Maximum pulse rate: max. 150Hz Geometric resolution (max), 0.5m

Spectral sampling: 2.5-10nm Bandwidth: 1024pixel z Radiometric resolution: 12bit

### OxTS RT 3003 high accuracy GPS/INS









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### Airborne hyperspectral imagery <u>Acquisition and results</u>

- High accuracy vegetation and landuse map
- High ground resolution (0.5-1.5 m)
  Vegetation associations level and
  species-level data extraction from
  classified hyperspectral data
  Supervised and unsupervised
  classification methods applied for
  - vegetation analysis.
  - Digital spatial database of the vegetation prepared by the determination of the biomass of the floodplain.
- Caracteristics of digital spatial database of the vegetation :
  - Geometric resolution: min.
     0.5\*0.5 pixel size
  - Accuracy: min. 75% reliability for each vegetation categories
  - Total accuracy: min. 80%
  - EOV and UTM34N

















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#### Vegetation map (Rakamaz – Nagy-Morotva)























#### NIR hyperspectral mosaic in project area





## Landuse map















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- The landuse classification was based on ground based reference points.
- Species-level data were recorded by sub-meter accuracy GPS device.
- The 0.5 m ground resolution geometrically and radiometrically corrected hyperspectral images and DTM and DSM layers, generated from the LIDAR data, were applied for the image classification.





#### **Biomass estimation**

- Several parameters used for tree biomass estimation:
- nDSM max: surface model produced from LIDAR DSM and DTM
- Canopy limit: surface smoothed canopy segments based on nDSM
- Tree species identification: classification performed on forest areas by the classification of hyperspectral images
- LIDAR layer indices: rates of the different reflectance values and intensity layer
- Cover test: for land cover assessment, model calculation was made by the Normalized Difference Vegetation Index (NDVI) calculated from the near infrared (799 nm) and red (677 nm) spectral channels of the hyperspectral image and the cover values measured on field.

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#### Ground based surveys (Tiszakeszi) Sample points



















Sample area (Tiszakeszi)



- The regression equation: determination of tree diameters from the LIDAR nDSM height data.
- Tree volume estimation according to Király's function (Király, 1968) by tree height and trunk diameter parameters.
- Application of other, predetermined parameters for the different tree species (totally 9 parameter groups).
- Calculation of the living wet density (t/m3) of different tree species by the tree volumes



















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# Integration of hyperspectral images, LIDAR data and aerial digital images

Hypelt Byeegetation (Marger GB)







# Ground based measurements - Geodetic surveys



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- Floodgates: coordinate, bottom level (flood side and saved side), upper level of the opening (diameter), top level of pit
- Mile stones: above sea level (mBf)
- Barriers (axle center point coordinate)
- Traffic signs: traffic and section boundary signs (coordinate),
- other crossings (pressure pipes, irrigation pipes, cables, roads, railways, product lines): coordinates, height measured in the dike axis in case of air wires



















# Dam bursting simulation Flood area 2D hydrodynamic model

- FloodArea is a 2D hydrodynamic application for the simulation of flood and dam burst.
- It is fully integrated in the ESRI ArcGIS 9.x (and ArcView 3.x) products, as an extension.
- Its main goal is to delineate the flooded areas during the flood.
  - Modeling of dam bursting scenarios
  - Controlled outlet of emergency flood reservoirs
  - Other functions:
    - Making simulation using different data sources
    - Inquiry of the temporal dynamics of flooding
      - Determination of flow direction and velocity





# Dam bursting simulation Flood area 2D hydrodynamic model











#### DTM with potential burst points (in red)





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# Thank you!



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